

# Machine Learning for Multi-step Ahead Forecasting of Volatility Proxies

Jacopo De Stefani, Ir. - [jdestefa@ulb.ac.be](mailto:jdestefa@ulb.ac.be)

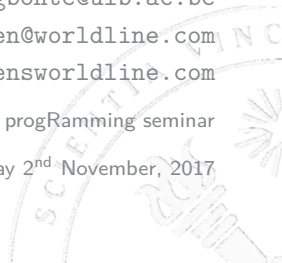
Prof. Gianluca Bontempi - [gbonte@ulb.ac.be](mailto:gbonte@ulb.ac.be)

Olivier Caelen, PhD - [olivier.caelen@worldline.com](mailto:olivier.caelen@worldline.com)

Dalila Hattab, PhD - [dalila.hattab@equensworldline.com](mailto:dalila.hattab@equensworldline.com)

INESC-ID - THOR: algoriTHms and cOmputer progRamming seminar

Lisbon, Thursday 2<sup>nd</sup> November, 2017



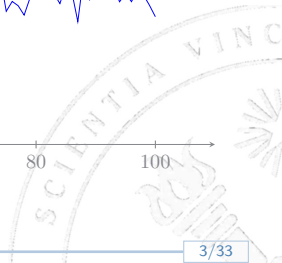
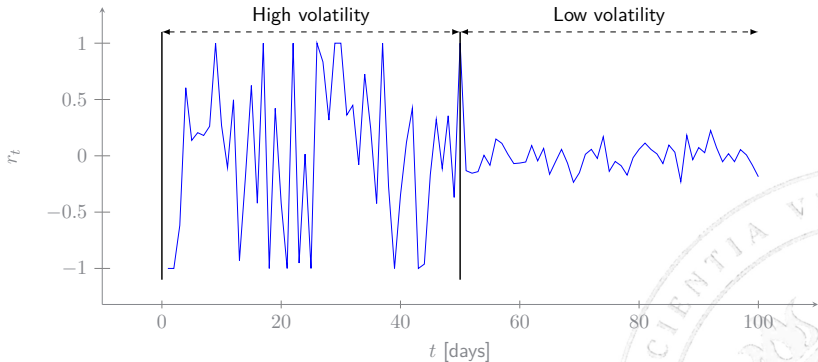
# Problem overview



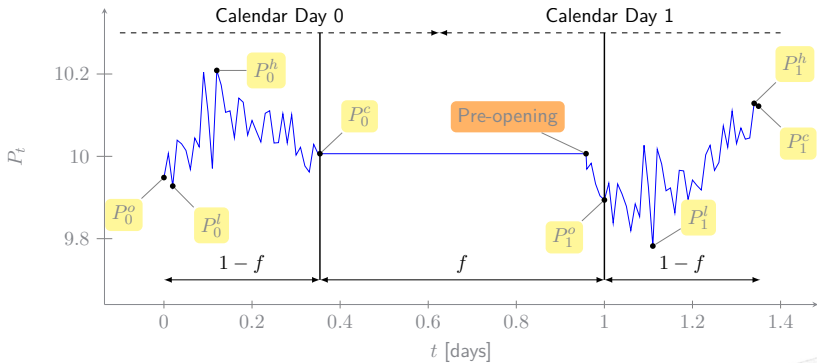
# What is volatility?

## Definition

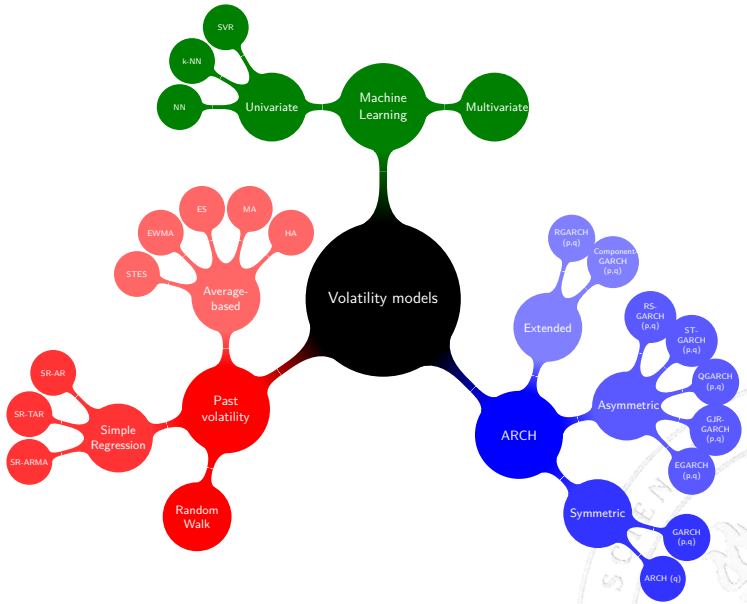
Volatility is a statistical measure of the dispersion of returns for a given security or market index.



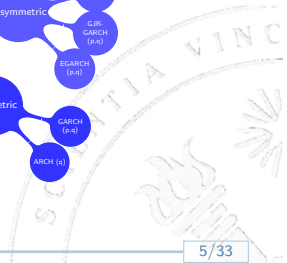
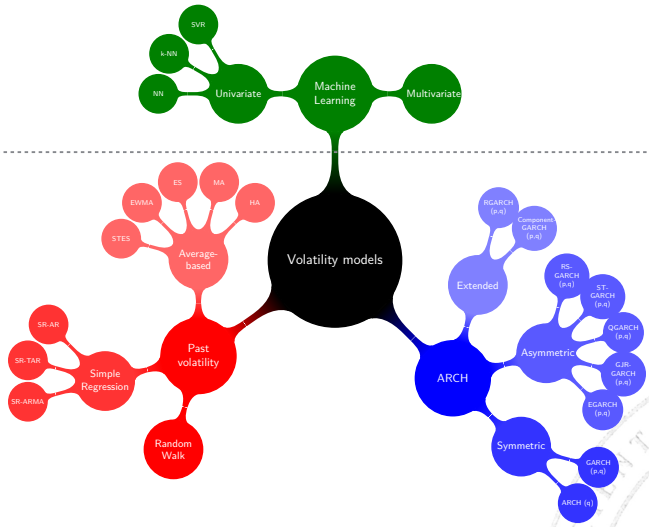
# A closer look on data - Volatility proxies



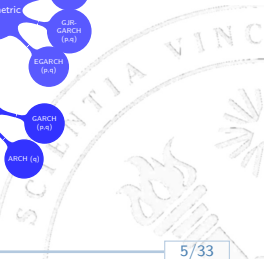
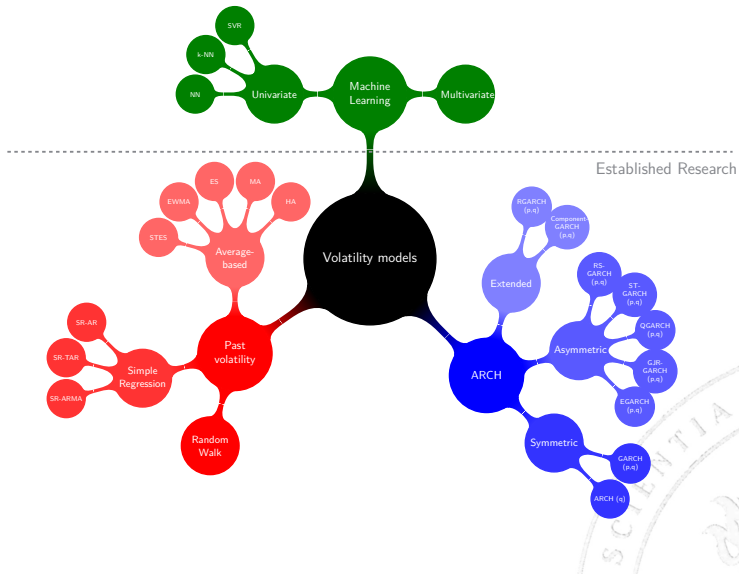
# Models for volatility



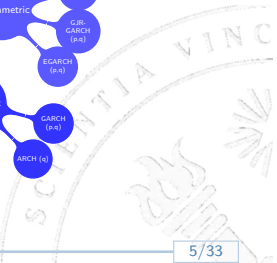
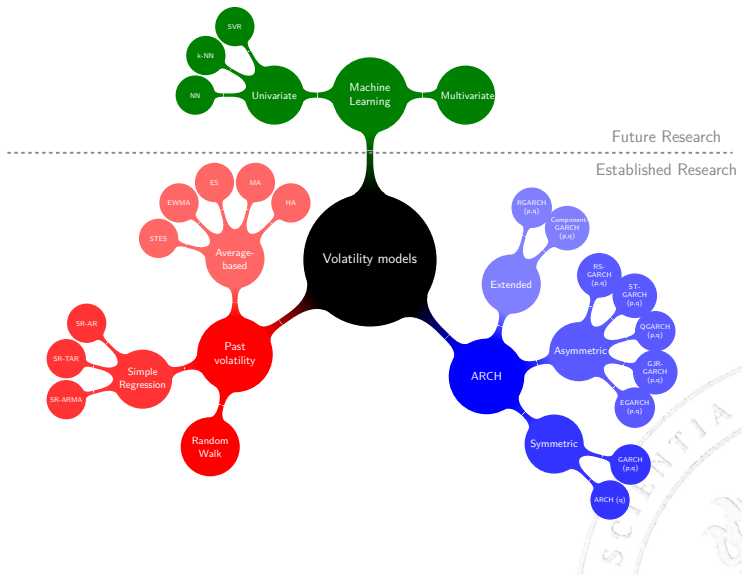
# Models for volatility



# Models for volatility



# Models for volatility





# Multistep ahead TS forecasting - ?

## Definition

Given a univariate time series  $\{y_1, \dots, y_T\}$  comprising  $T$  observations, forecast the next  $H$  observations  $\{y_{T+1}, \dots, y_{T+H}\}$  where  $H$  is the forecast horizon.

## Hypotheses:

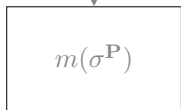
- ▶ Autoregressive model  $y_t = m(y_{t-1}, \dots, y_{t-d}) + \varepsilon_t$  with lag order (embedding)  $d$
- ▶  $\varepsilon$  is a stochastic iid model with  $\mu_\varepsilon = 0$  and  $\sigma_\varepsilon^2 = \sigma^2$



# Multistep ahead forecasting for volatility

State-of-the-art  
NAR

$$[\sigma_{t-d}^P \quad \cdots \quad \sigma_{t-1}^P]$$



$$[\hat{\sigma}_t^P \quad \cdots \quad \hat{\sigma}_{t+H}^P]$$

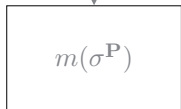
1 Input  
1 Output



# Multistep ahead forecasting for volatility

State-of-the-art  
NAR

$$[\sigma_{t-d}^P \quad \cdots \quad \sigma_{t-1}^P]$$

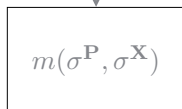


$$[\hat{\sigma}_t^P \quad \cdots \quad \hat{\sigma}_{t+H}^P]$$

1 Input  
1 Output

Proposed model  
NARX

$$\begin{bmatrix} \sigma_{t-d}^P & \cdots & \sigma_{t-1}^P \\ \sigma_{t-d}^X & \cdots & \sigma_{t-1}^X \end{bmatrix}$$



$$[\hat{\sigma}_t^P \quad \cdots \quad \hat{\sigma}_{t+H}^P]$$

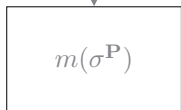
2 inputs  
1 output



# Multistep ahead forecasting for volatility

State-of-the-art  
NAR

$$[\sigma_{t-d}^P \quad \cdots \quad \sigma_{t-1}^P]$$

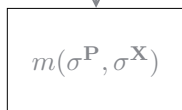


$$[\hat{\sigma}_t^P \quad \cdots \quad \hat{\sigma}_{t+H}^P]$$

1 Input  
1 Output

Proposed model  
NARX

$$\begin{bmatrix} \sigma_{t-d}^P & \cdots & \sigma_{t-1}^P \\ \sigma_{t-d}^X & \cdots & \sigma_{t-1}^X \end{bmatrix}$$

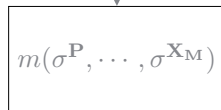


$$[\hat{\sigma}_t^P \quad \cdots \quad \hat{\sigma}_{t+H}^P]$$

2 inputs  
1 output

Future work

$$\begin{bmatrix} \sigma_{t-d}^P & \cdots & \sigma_{t-1}^P \\ \cdots & \cdots & \cdots \\ \sigma_{t-d}^{X_M} & \cdots & \sigma_{t-1}^{X_M} \end{bmatrix}$$



$$\begin{bmatrix} \hat{\sigma}_t^P & \cdots & \hat{\sigma}_{t+H}^P \\ \cdots & \cdots & \cdots \\ \hat{\sigma}_t^{X_M} & \cdots & \hat{\sigma}_{t+H}^{X_M} \end{bmatrix}$$

M + 1 inputs  
M + 1 outputs

# Multistep ahead forecasting for volatility

## Direct method

- ▶ A single model  $f^h$  for each horizon  $h$ .
- ▶ Forecast at  $h$  step is made using  $h^{\text{th}}$  model.
- ▶ Dataset examples ( $d = 3, h = 3$ ):

### Direct NAR

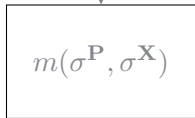
x			y
$\sigma_3^P$	$\sigma_2^P$	$\sigma_1^P$	$\sigma_5^P$
$\sigma_4^P$	$\sigma_3^P$	$\sigma_2^P$	$\sigma_6^P$
...	...	...	...
$\sigma_{T-5}^P$	$\sigma_{T-6}^P$	$\sigma_{T-7}^P$	$\sigma_{T-2}^P$

### Direct NARX

x						y
$\sigma_3^P$	$\sigma_2^P$	$\sigma_1^P$	$\sigma_3^X$	$\sigma_2^X$	$\sigma_1^X$	$\sigma_5^P$
$\sigma_4^P$	$\sigma_3^P$	$\sigma_2^P$	$\sigma_4^X$	$\sigma_3^X$	$\sigma_2^X$	$\sigma_6^P$
...	...	...	...	...	...	...
$\sigma_{T-5}^P$	$\sigma_{T-6}^P$	$\sigma_{T-7}^P$	$\sigma_{T-5}^X$	$\sigma_{T-6}^X$	$\sigma_{T-7}^X$	$\sigma_{T-2}^P$

# Experimental setup

$$\begin{bmatrix} \sigma_{t-d}^P & \cdots & \sigma_{t-1}^P \\ \sigma_{t-d}^X & \cdots & \sigma_{t-1}^X \end{bmatrix}$$



$$[\hat{\sigma}_t^P \quad \cdots \quad \hat{\sigma}_{t+H}^P]$$

**2 TS Input**  
**1 TS Output**

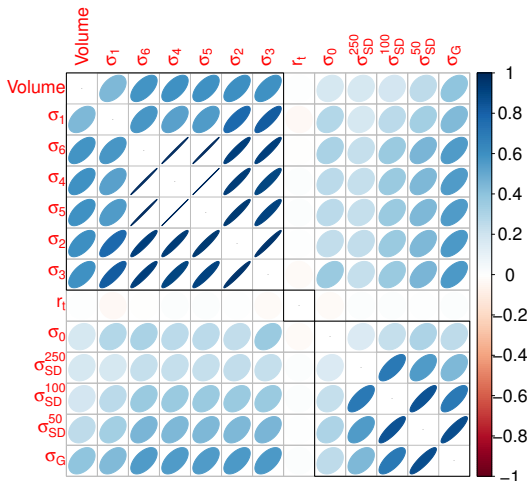
**Data:** Volatility proxies  $\sigma^X$ ,  $\sigma^P$  from CAC40:

- ▶ Price based
  - ▶  $\sigma_i$  family - ?
- ▶ Return based
  - ▶ GARCH (1,1) model - ?
  - ▶ Sample standard deviation

**Models:**

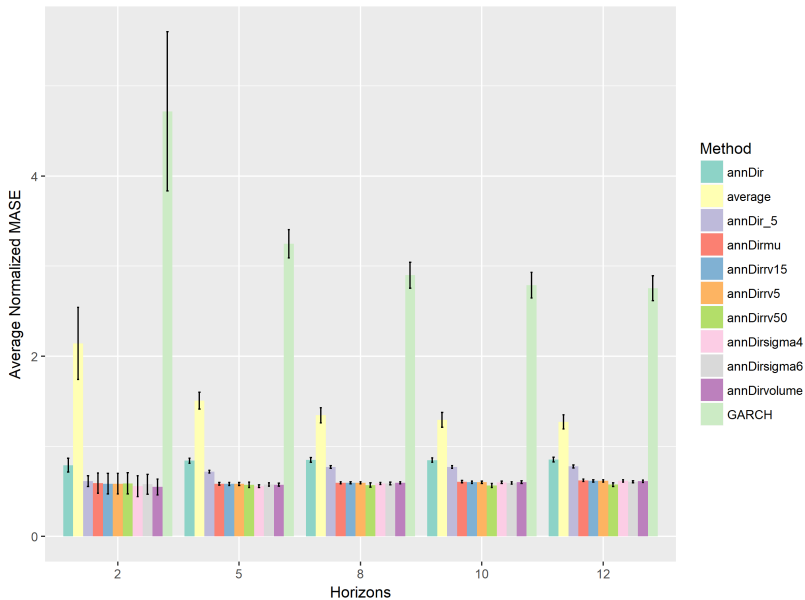
- ▶ Feedforward Neural Networks (NAR, NARX)
- ▶ k-Nearest Neighbors (NAR, NARX)
- ▶ Support Vector Regression (NAR, NARX)
- ▶ Naive (w/o  $\sigma^X$ )
- ▶ GARCH(1,1) (w/o  $\sigma^X$ )
- ▶ Average (w/o  $\sigma^X$ )

## Correlation meta-analysis (cf. ?)



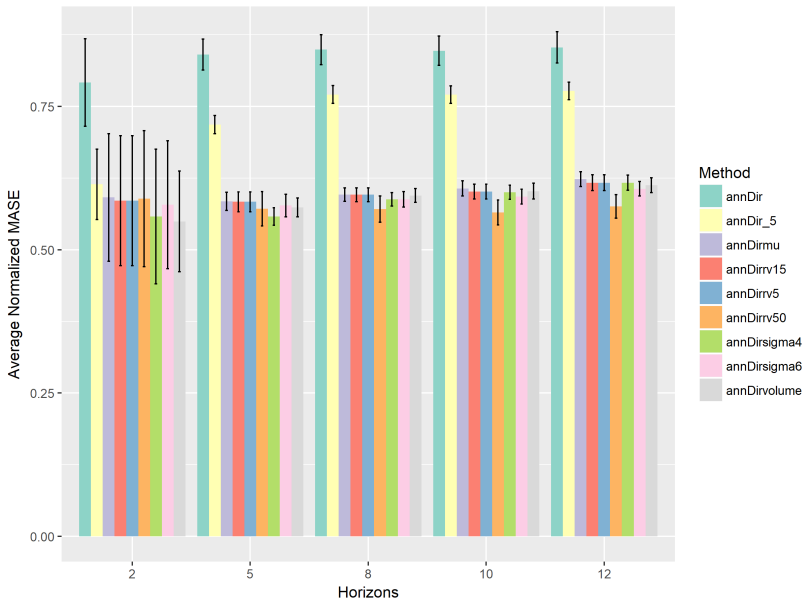
- ▶ 40 time series (CAC40)
- ▶ Time range: 05-01-2009 to 22-10-2014
- ▶ 1489 OHLC samples per TS
- ▶ Hierarchical clustering using ?
- ▶ All correlations are statistically significant

## NARX forecaster - Results ANN

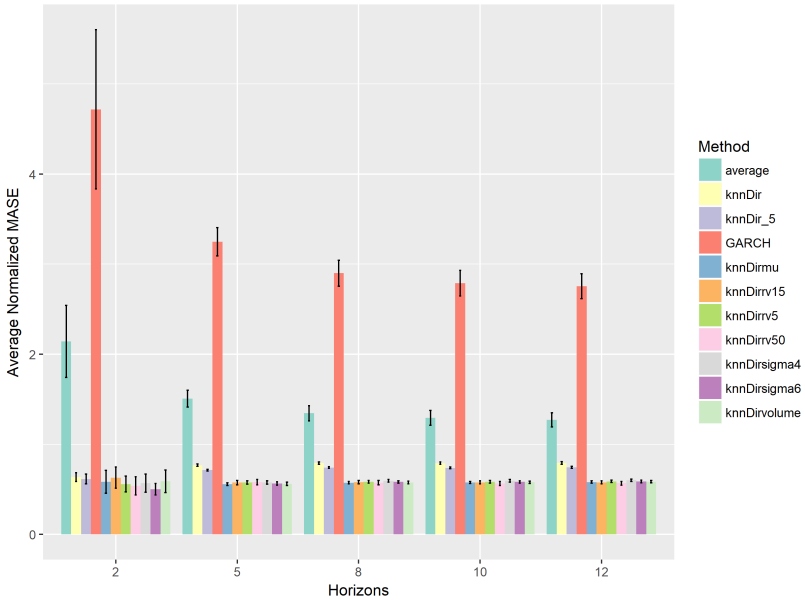




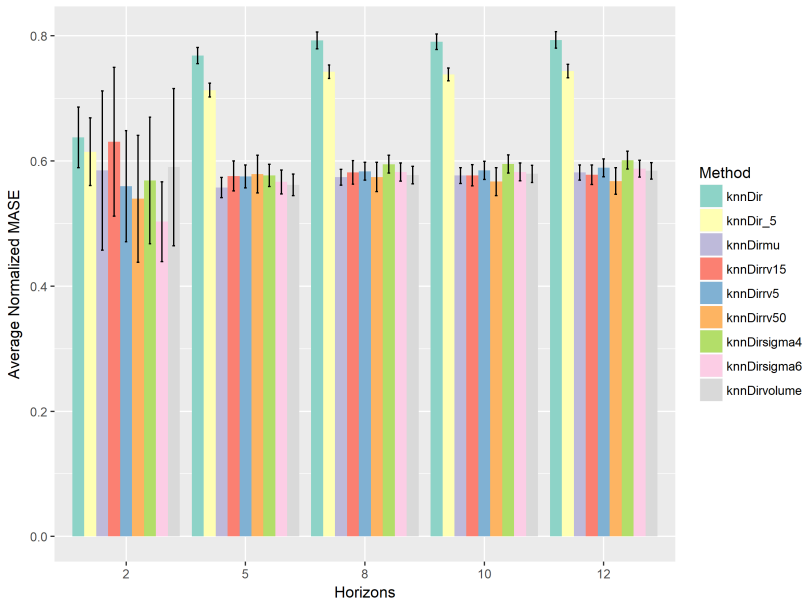
## NARX forecaster - Results ANN



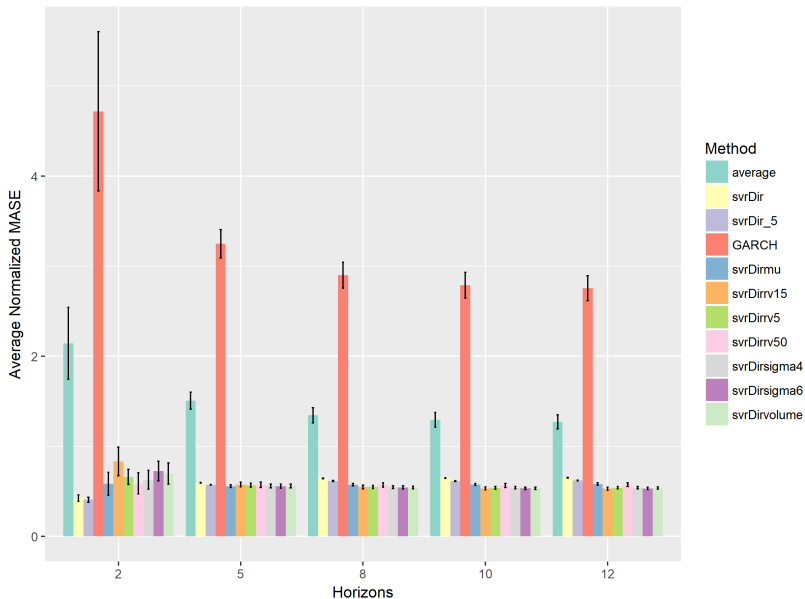
# NARX forecaster - Results KNN



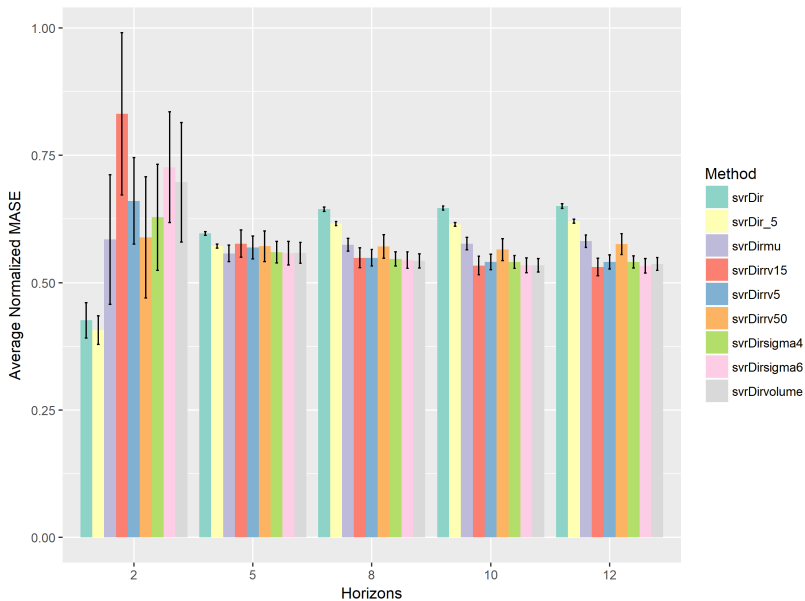
## NARX forecaster - Results KNN



## NARX forecaster - Results SVR



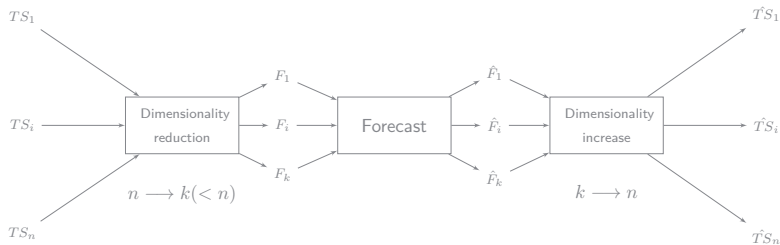
## NARX forecaster - Results SVR



# Conclusions

- ▶ Correlation clustering among proxies belonging to the same family, i.e.  $\sigma_t^i$  and  $\sigma_t^{SD,n}$ .
- ▶ All ML methods outperform the reference GARCH method, both in the single input and the multiple input configuration.
- ▶ Only the addition of an external regressor, and for  $h > 8$  bring a statistically significant improvement (paired t-test,  $p=0.05$ ).
- ▶ No model appear to clearly outperform all the others on every horizons, but generally SVR performs better than ANN and k-NN.

# Multivariate extension - DFML - ?



## Dimensionality reduction/increase

- ▶ PCA
- ▶ Autoencoder

## Forecast

- ▶ Lazy Learning
- ▶ Vector Auto Regressive

Outperforms Recurrent Neural Network, Partial Least Squares, Vector Auto Regressive, Singular Spectrum Analysis, Univariate and Naive.

# Future work - Open problems

- ▶ Efficient multivariate predictive models?
- ▶ Large scale dimensionality reduction techniques?
  - ▶ Component-iterative PCA
  - ▶ Sample-iterative PCA
  - ▶ Autoencoders
- ▶ Streaming approaches to multivariate forecasting?





Obrigado pela vossa atenção! Alguma pergunta/observação?

`jacopo.de.stefani@ulb.ac.be`



Find the paper at:



Open vacancy - Post-doc:

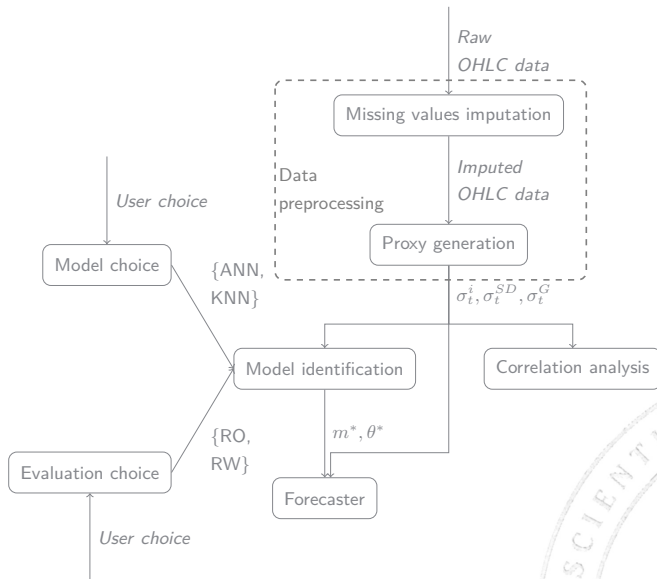


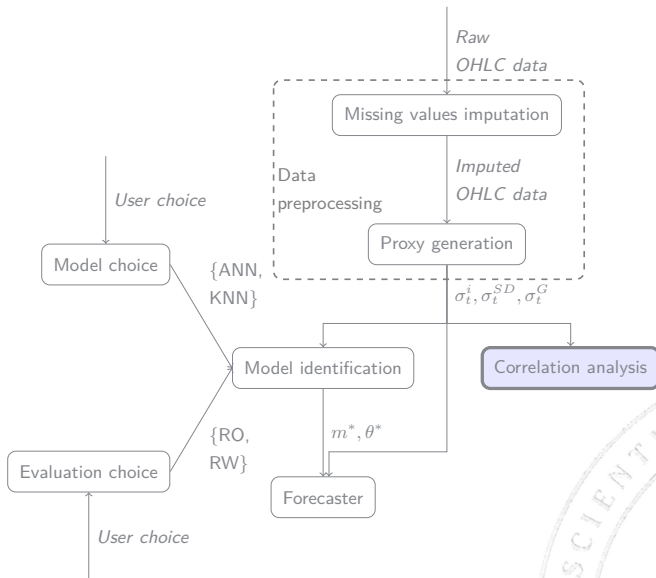
## References

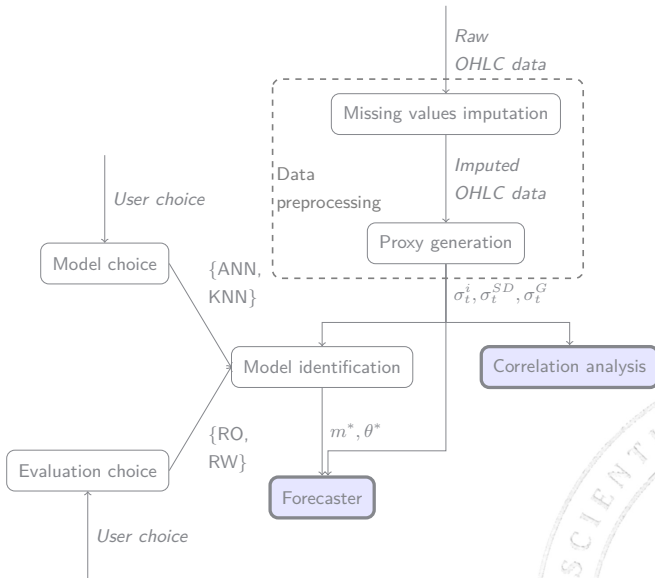


# Appendix

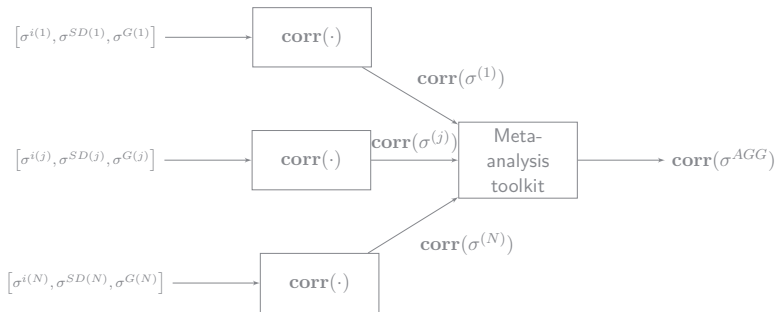






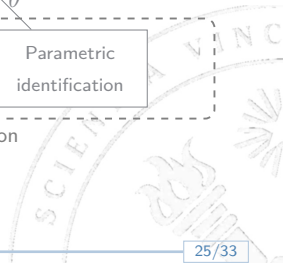
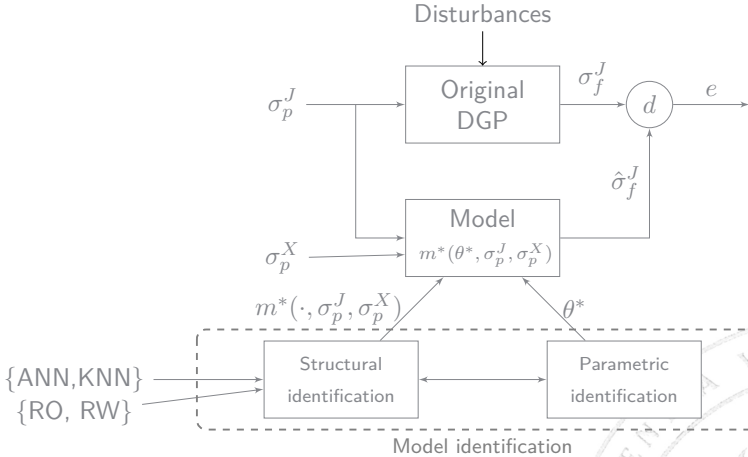


# Correlation analysis - Methodology



- ▶ 40 Time series (CAC40)
- ▶ Time range: 05-01-2009 to 22-10-2014 ⇒ 1489 OHLC samples per TS

# NARX forecaster - Methodology





# Volatility proxies (1) - ?

- ▶ Closing prices

$$\hat{\sigma}_0(t) = \left[ \ln \left( \frac{P_{t+1}^{(c)}}{P_t^{(c)}} \right) \right]^2 = r_t^2 \quad (1)$$

- ▶ Opening/Closing prices

$$\hat{\sigma}_1(t) = \underbrace{\frac{1}{2f} \cdot \left[ \ln \left( \frac{P_{t+1}^{(o)}}{P_t^{(c)}} \right) \right]^2}_{\text{Nightly volatility}} + \underbrace{\frac{1}{2(1-f)} \cdot \left[ \ln \left( \frac{P_t^{(c)}}{P_t^{(o)}} \right) \right]^2}_{\text{Intraday volatility}} \quad (2)$$

- ▶ OHLC prices

$$\hat{\sigma}_2(t) = \frac{1}{2 \ln 4} \cdot \left[ \ln \left( \frac{P_t^{(h)}}{P_t^{(l)}} \right) \right]^2 \quad (3)$$

$$\hat{\sigma}_3(t) = \underbrace{\frac{a}{f} \cdot \left[ \ln \left( \frac{P_{t+1}^{(o)}}{P_t^{(c)}} \right) \right]^2}_{\text{Nightly volatility}} + \underbrace{\frac{1-a}{1-f} \cdot \hat{\sigma}_2(t)}_{\text{Intraday volatility}} \quad (4)$$

## Volatility proxies (2) - ?

► OHLC prices

$$u = \ln \left( \frac{P_t^{(h)}}{P_t^{(o)}} \right) \quad d = \ln \left( \frac{P_t^{(l)}}{P_t^{(o)}} \right) \quad c = \ln \left( \frac{P_t^{(c)}}{P_t^{(o)}} \right) \quad (5)$$

$$\hat{\sigma}_4(t) = 0.511(u - d)^2 - 0.019[c(u + d) - 2ud] - 0.383c^2 \quad (6)$$

$$\hat{\sigma}_5(t) = 0.511(u - d)^2 - (2 \ln 2 - 1)c^2 \quad (7)$$

$$\hat{\sigma}_6(t) = \underbrace{\frac{a}{f} \cdot \log \left( \frac{P_{t+1}^{(o)}}{P_t^{(c)}} \right)^2}_{\text{Nightly volatility}} + \underbrace{\frac{1-a}{1-f} \cdot \hat{\sigma}_4(t)}_{\text{Intraday volatility}} \quad (8)$$

## Volatility proxies (3)

- GARCH (1,1) model - ?

$$\sigma_t^G = \sqrt{\omega + \sum_{j=1}^p \beta_j (\sigma_{t-j}^G)^2 + \sum_{i=1}^q \alpha_i \varepsilon_{t-i}^2}$$

where  $\varepsilon_{t-i} \sim \mathcal{N}(0, 1)$ , with the coefficients  $\omega, \alpha_i, \beta_j$  fitted according to ?

- Sample standard deviation

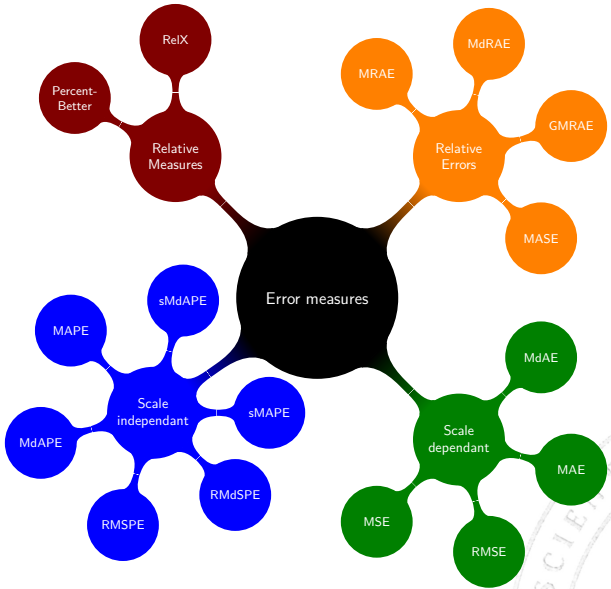
$$\sigma_t^{SD,n} = \sqrt{\frac{1}{n-1} \sum_{i=0}^{n-1} (r_{t-i} - \bar{r})^2}$$

where

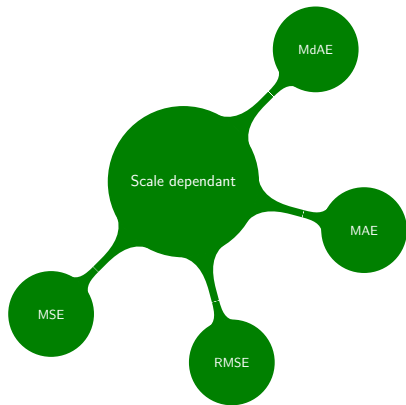
$$r_t = \ln \left( \frac{P_t^{(c)}}{P_{t-1}^{(c)}} \right)$$

$$\bar{r}_n = \frac{1}{n} \sum_{j=t-n}^t r_j$$

# ? - Error measures



# ? - Scale dependant



$$e_t = y_t - \hat{y}_t$$

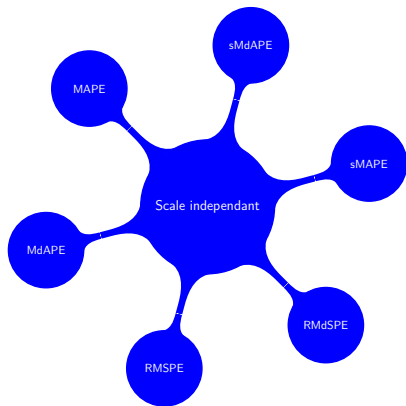
▶ **MSE** :  $\frac{1}{n} \sum_{t=0}^n (y_t - \hat{y}_t)^2$

▶ **RMSE** :  $\sqrt{\frac{1}{n} \sum_{t=0}^n (y_t - \hat{y}_t)^2}$

▶ **MAE** :  $\frac{1}{n} \sum_{t=0}^n |y_t - \hat{y}_t|$

▶ **MdAE** :  
 $Md_{t \in \{1 \dots n\}} (|y_t - \hat{y}_t|)$

## ? - Scale independant

▶ **MAPE :**

$$\frac{1}{n} \sum_{t=0}^n \left| 100 \cdot \frac{y_t - \hat{y}_t}{y_t} \right|$$

▶ **MdAPE :**

$$Md_{t \in \{1 \dots n\}} \left( \left| 100 \cdot \frac{y_t - \hat{y}_t}{y_t} \right| \right)$$

▶ **RMSPE :**

$$\sqrt{\frac{1}{n} \sum_{t=0}^n \left( 100 \cdot \frac{y_t - \hat{y}_t}{y_t} \right)^2}$$

▶ **RMdSPE :**

$$\sqrt{Md_{t \in \{1 \dots n\}} \left( \left( 100 \cdot \frac{y_t - \hat{y}_t}{y_t} \right)^2 \right)}$$

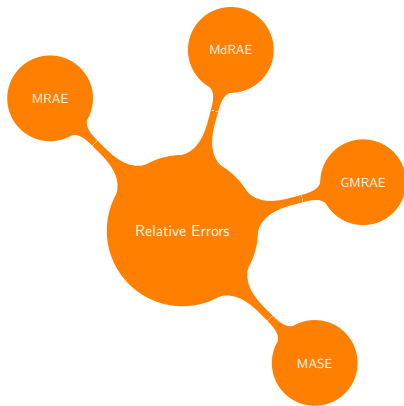
▶ **sMAPE :**

$$\frac{1}{n} \sum_{t=0}^n 200 \cdot \frac{|y_t - \hat{y}_t|}{y_t + \hat{y}_t}$$

▶ **sMdAPE :**

$$Md_{t \in \{1 \dots n\}} \left( 200 \cdot \frac{|y_t - \hat{y}_t|}{y_t + \hat{y}_t} \right)$$

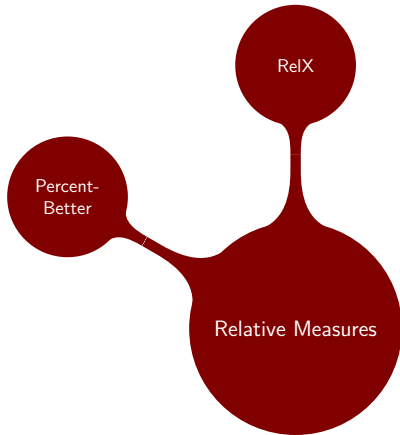
## ? - Relative errors



$$r_t = \frac{e_t}{e_t^*}$$

- ▶ **MRAE** :  $\frac{1}{n} \sum_{t=0}^n |r_t|$
- ▶ **MdRAE** :  $Md_{t \in \{1 \dots n\}}(|r_t|)$
- ▶ **GMRAE** :  $\sqrt[n]{\frac{1}{n} \prod_{t=0}^n |r_t|}$
- ▶ **MASE** :  $\frac{1}{T} \sum_{t=1}^T \left( \frac{|e_t|}{\frac{1}{T-1} \sum_{i=2}^T |Y_i - Y_{i-1}|} \right)$

## ? - Relative measures



▶ **RelX** :  $\frac{X}{X_{\text{bench}}}$

▶ **Percent Better** :

$$PB(X) =$$

$$100 \cdot \frac{1}{n} \sum_{\text{forecasts}} I(X < X_b)$$

where

- ▶  $X$ : Error measure of the analyzed method
- ▶  $X_b$ : Error measure of the benchmark